

Lagrangians and Hamiltonians in Classical Field Theory

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Lagrangians and Hamiltonians in Classical Field Theory

Lagrangian and Hamiltonian formulations of field theories play a central role in their quantization.

However, it had been my view that their role in classical field theory was not much more than that of a mnemonic device to remember the field equations. When I wrote my GR text, the discussion of the Lagrangian (Einstein-Hilbert) and Hamiltonian (ADM) formulations of general relativity was relegated to an appendix. My views have changed dramatically in the past 15 years:

The existence of a Lagrangian or Hamiltonian provides important auxiliary structure to a classical field theory, which endows the theory with key properties.

Lagrangians and Hamiltonians in Particle Mechanics

Consider particle paths $q(t)$. If L is a function of (q, \dot{q}) , then we have the identity

$$\delta L = \left[\frac{\partial L}{\partial q} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} \right] \delta q + \frac{d}{dt} \left[\frac{\partial L}{\partial \dot{q}} \delta q \right]$$

holding at each time t . L is a Lagrangian for the system if the equations of motion are

$$0 = E \equiv \frac{\partial L}{\partial q} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}}$$

The “boundary term”

$$\Theta(q, \dot{q}) \equiv \frac{\partial L}{\partial \dot{q}} \delta q = p \delta q$$

(with $p \equiv \partial L / \partial \dot{q}$) is usually discarded. However, by taking a second, antisymmetrized variation of Θ and evaluating at time t_0 , we obtain the quantity

$$\begin{aligned}\Omega(q, \delta_1 q, \delta_2 q) &= [\delta_1 \Theta(q, \delta_2 q) - \delta_2 \Theta(q, \delta_1 q)]|_{t_0} \\ &= [\delta_1 p \delta_2 q - \delta_2 p \delta_1 q]|_{t_0}\end{aligned}$$

Then Ω is independent of t_0 provided that the varied paths $\delta_1 q(t)$ and $\delta_2 q(t)$ satisfy the linearized equations of motion about $q(t)$. Ω is highly degenerate on the infinite dimensional space of all paths \mathcal{F} , but if we factor \mathcal{F} by the degeneracy subspaces of Ω , we obtain a finite dimensional *phase space* Γ on which Ω is non-degenerate. A *Hamiltonian*, H , is a function on Γ whose pullback to

\mathcal{F} satisfies

$$\delta H = \Omega(q; \delta q, \dot{q})$$

for all δq provided that $q(t)$ satisfies the equations of motion. This is equivalent to saying that the equations of motion are

$$\dot{q} = \frac{\partial H}{\partial p} \qquad \dot{p} = -\frac{\partial H}{\partial q}$$

Lagrangians and Hamiltonians in Classical Field Theory

Let ϕ denote the collection of dynamical fields. The analog of \mathcal{F} is the space of field configurations on spacetime. For an n -dimensional spacetime, a Lagrangian \mathbf{L} is most naturally viewed as an n -form on spacetime that is a function of ϕ and finitely many of its derivatives. Variation of \mathbf{L} yields

$$\delta\mathbf{L} = \mathbf{E}\delta\phi + d\Theta$$

where Θ is an $(n - 1)$ -form on spacetime, locally constructed from ϕ and $\delta\phi$. The equations of motion are then $\mathbf{E} = 0$. The symplectic current ω is defined by

$$\omega(\phi, \delta_1\phi, \delta_2\phi) = \delta_1\Theta(\phi, \delta_2\phi) - \delta_2\Theta(\phi, \delta_1\phi)$$

and Ω is then defined by

$$\Omega(\phi, \delta_1\phi, \delta_2\phi) = \int_{\Sigma} \omega(\phi, \delta_1\phi, \delta_2\phi)$$

where Σ is a Cauchy surface. Phase space is constructed by factoring field configuration space by the degeneracy subspaces of Ω , and a Hamiltonian, H_{ξ} , conjugate to a vector field ξ^a on spacetime is a function on phase space whose pullback to field configuration space satisfies

$$\delta H_{\xi} = \Omega(\phi; \delta\phi, \mathcal{L}_{\xi}\phi)$$

Diffeomorphism Covariant Theories

A diffeomorphism covariant theory is one whose Lagrangian is constructed entirely from dynamical fields, i.e., there is no “background structure” in the theory apart from the manifold structure of spacetime. For a diffeomorphism covariant theory for which dynamical fields, ϕ , are a metric g_{ab} and tensor fields ψ , the Lagrangian takes the form

$$\mathbf{L} = \mathbf{L} \left(g_{ab}, R_{bcde}, \dots, \nabla_{(a_1} \dots \nabla_{a_m)} R_{bcde}; \psi, \dots, \nabla_{(a_1} \dots \nabla_{a_l)} \psi \right)$$

Noether Current and Noether Charge

For a diffeomorphism covariant theory, every vector field ξ^a on spacetime generates a local symmetry. We associate to each ξ^a and each field configuration, ϕ (*not* required, at this stage, to be a solution of the equations of motion), a Noether current $(n - 1)$ -form, \mathbf{J}_ξ , defined by

$$\mathbf{J}_\xi = \Theta(\phi, \mathcal{L}_\xi \phi) - \xi \cdot \mathbf{L}$$

A simple calculation yields

$$d\mathbf{J}_\xi = -\mathbf{E}\mathcal{L}_\xi \phi$$

which shows \mathbf{J}_ξ is closed (for all ξ^a) when the equations of motion are satisfied. It can then be shown that for all

ξ^a and all ϕ (not required to be a solution to the equations of motion), we can write \mathbf{J}_ξ as

$$\mathbf{J}_\xi = \xi^a \mathbf{C}_a + d\mathbf{Q}_\xi$$

where $\mathbf{C}_a = 0$ are the constraint equations of the theory and \mathbf{Q}_ξ is an $(n - 2)$ -form locally constructed out of the dynamical fields ϕ , the vector field ξ^a , and finitely many of their derivatives. It can be shown that \mathbf{Q}_ξ can always be expressed in the form

$$\mathbf{Q}_\xi = \mathbf{W}_c(\phi)\xi^c + \mathbf{X}^{cd}(\phi)\nabla_{[c}\xi_{d]} + \mathbf{Y}(\phi, \mathcal{L}_\xi\phi) + d\mathbf{Z}(\phi, \xi)$$

Furthermore, there is some “gauge freedom” in the choice of \mathbf{Q}_ξ arising from (i) the freedom to add an exact form to the Lagrangian, (ii) the freedom to add an exact

form to Θ , and (iii) the freedom to add an exact form to Q_ξ . Using this freedom, we may choose Q_ξ to take the form

$$Q_\xi = W_c(\phi)\xi^c + X^{cd}(\phi)\nabla_{[c}\xi_{d]}$$

where

$$(X^{cd})_{c_3\dots c_n} = -E_R^{abcd}\epsilon_{abc_3\dots c_n}$$

where $E_R^{abcd} = 0$ are the equations of motion that would result from pretending that R_{abcd} were an independent dynamical field in the Lagrangian L .

Hamiltonians

Let ϕ be any solution of the equations of motion, and let $\delta\phi$ be any variation of the dynamical fields (not necessarily satisfying the linearized equations of motion) about ϕ . Let ξ^a be an arbitrary, fixed vector field. We then have

$$\begin{aligned}\delta\mathbf{J}_\xi &= \delta\Theta(\phi, \mathcal{L}_\xi\phi) - \xi \cdot \delta\mathbf{L} \\ &= \delta\Theta(\phi, \mathcal{L}_\xi\phi) - \xi \cdot d\Theta(\phi, \delta\phi) \\ &= \delta\Theta(\phi, \mathcal{L}_\xi\phi) - \mathcal{L}_\xi\Theta(\phi, \delta\phi) + d(\xi \cdot \Theta(\phi, \delta\phi))\end{aligned}$$

On the other hand, we have

$$\delta\Theta(\phi, \mathcal{L}_\xi\phi) - \mathcal{L}_\xi\Theta(\phi, \delta\phi) = \omega(\phi, \delta\phi, \mathcal{L}_\xi\phi)$$

We therefore obtain

$$\omega(\phi, \delta\phi, \mathcal{L}_\xi\phi) = \delta\mathbf{J}_\xi - d(\xi \cdot \Theta)$$

Replacing \mathbf{J}_ξ by $\xi^a \mathbf{C}_a + d\mathbf{Q}_\xi$ and integrating over a Cauchy surface Σ , we obtain

$$\begin{aligned}\Omega(\phi, \delta\phi, \mathcal{L}_\xi\phi) &= \int_\Sigma [\xi^a \delta\mathbf{C}_a + \delta d\mathbf{Q}_\xi - d(\xi \cdot \Theta)] \\ &= \int_\Sigma \xi^a \delta\mathbf{C}_a + \int_{\partial\Sigma} [\delta Q_\xi - \xi \cdot \Theta]\end{aligned}$$

The $(n - 1)$ -form Θ cannot be written as the variation of a quantity locally and covariantly constructed out of the dynamical fields (unless $\omega = 0$). However, it is possible that for the class of spacetimes being considered,

we can find a (not necessarily diffeomorphism covariant) $(n - 1)$ -form, \mathbf{B} , such that

$$\delta \int_{\partial\Sigma} \xi \cdot \mathbf{B} = \int_{\partial\Sigma} \xi \cdot \mathbf{\Theta}$$

A Hamiltonian for the dynamics generated by ξ^a exist on this class of spacetimes if and only if such a \mathbf{B} exists. This Hamiltonian is then given by

$$H_\xi = \int_{\Sigma} \xi^a \mathbf{C}_a + \int_{\partial\Sigma} [\mathbf{Q}_\xi - \xi \cdot \mathbf{B}]$$

Note that “on shell”, i.e., when the field equations are satisfied, we have $\mathbf{C}_a = 0$ so the Hamiltonian is purely a “surface term”.

Energy and Angular Momentum

If a Hamiltonian conjugate to a time translation $\xi^a = t^a$ exists, we define the *energy*, \mathcal{E} of a solution $\phi = (g_{ab}, \psi)$ by

$$\mathcal{E} \equiv H_t = \int_{\partial\Sigma} (\mathbf{Q}_t - t \cdot \mathbf{B})$$

Similarly, if a Hamiltonian, H_φ , conjugate to a rotation $\xi^a = \varphi^a$ exists, we define the *angular momentum*, \mathcal{J} of a solution by

$$\mathcal{J} \equiv -H_\varphi = - \int_{\partial\Sigma} [\mathbf{Q}_\varphi - \varphi \cdot \mathbf{B}]$$

If φ^a is tangent to Σ , the last term vanishes, and we

obtain simply

$$\mathcal{J} = - \int_{\partial\Sigma} \mathbf{Q}_\varphi$$

Energy and Angular Momentum in General Relativity:

ADM vs Komar

In general relativity in 4 dimensions, the Einstein-Hilbert Lagrangian is

$$\mathbf{L}_{abcd} = \frac{1}{16\pi} \epsilon_{abcd} R$$

This yields the symplectic potential 3-form

$$\Theta_{abc} = \epsilon_{dabc} \frac{1}{16\pi} g^{de} g^{fh} (\nabla_f \delta g_{eh} - \nabla_e \delta g_{fh}).$$

The corresponding Noether current and Noether charge are

$$(\mathbf{J}_\xi)_{abc} = \frac{1}{8\pi} \epsilon_{dabc} \nabla_e (\nabla^{[e} \xi^{d]}),$$

and

$$(\mathbf{Q}_\xi)_{ab} = -\frac{1}{16\pi} \epsilon_{abcd} \nabla^c \xi^d.$$

For asymptotically flat spacetimes, the formula for angular momentum conjugate to an asymptotic rotation φ^a is

$$\mathcal{J} = \frac{1}{16\pi} \int_\infty \epsilon_{abcd} \nabla^c \varphi^d$$

This agrees with the ADM expression, and when φ^a is a Killing vector field, it agrees with the Komar formula. For an asymptotic time translation t^a , a Hamiltonian, H_t , exists with

$$t^a \mathbf{B}_{abc} = -\frac{1}{16\pi} \tilde{\epsilon}_{bc} \left((\partial_r g_{tt} - \partial_t g_{rt}) + r^k h^{ij} (\partial_i h_{kj} - \partial_k h_{ij}) \right)$$

The corresponding Hamiltonian

$$H_t = \int_{\Sigma} t^a \mathbf{C}_a + \frac{1}{16\pi} \int_{\infty} dS r^k h^{ij} (\partial_i h_{kj} - \partial_k h_{ij})$$

is precisely the ADM Hamiltonian, and the surface term is the ADM mass,

$$M_{\text{ADM}} = \frac{1}{16\pi} \int_{\infty} dS r^k h^{ij} (\partial_i h_{kj} - \partial_k h_{ij})$$

By contrast, if t^a is a Killing field, the Komar expression

$$M_{\text{Komar}} = -\frac{1}{8\pi} \int_{\infty} \epsilon_{abcd} \nabla^c t^d$$

happens to give the correct (ADM) answer, but this is merely a fluke.

The First Law of Black Hole Mechanics

Return to a general, diffeomorphism covariant theory, and recall that for any solution ϕ , any $\delta\phi$ (not necessarily a solution of the linearized equations) and any ξ^a , we have

$$\Omega(\phi, \delta\phi, \mathcal{L}_\xi\phi) = \int_\Sigma \xi^a \delta\mathbf{C}_a + \int_{\partial\Sigma} [\delta Q_\xi - \xi \cdot \Theta]$$

Now suppose that ϕ is a stationary black hole with a Killing horizon with bifurcation surface \mathcal{H} . Let ξ^a denote the horizon Killing field, so that $\xi^a|_{\mathcal{H}} = 0$ and

$$\xi^a = t^a + \Omega_H \varphi^a$$

Then $\mathcal{L}_\xi\phi = 0$. Let $\delta\phi$ satisfy the linearized equations, so $\delta\mathbf{C}_a = 0$. Let Σ be a hypersurface extending from \mathcal{H}

to infinity.

$$0 = \int_{\infty} [\delta Q_{\xi} - \xi \cdot \Theta) - \int_{\mathcal{H}} \delta Q_{\xi}$$

Thus, we obtain

$$\delta \int_{\mathcal{H}} Q_{\xi} = \delta \mathcal{E} - \Omega_H \delta \mathcal{J}$$

Furthermore, from the formula for Q_{ξ} and the properties of Killing horizons, one can show that

$$\delta \int_{\mathcal{H}} Q_{\xi} = \frac{\kappa}{2\pi} \delta S$$

where S is defined by

$$S = 2\pi \int_{\mathcal{H}} \mathbf{X}^{cd} \epsilon_{cd}$$

where ϵ_{cd} denotes the binormal to \mathcal{H} . Thus, we have shown that the first law of black hole mechanics

$$\frac{\kappa}{2\pi} \delta S = \delta \mathcal{E} - \Omega_H \delta \mathcal{J}$$

holds in an arbitrary diffeomorphism covariant theory of gravity, and we have obtained an explicit formula for black hole entropy S .

Variational Principle for Stability

Suppose one is interested in the stability of a stationary solution, ϕ , of the field equations. In certain cases—such as spherically symmetric perturbations of static, spherically solutions of Einstein-fluid equations—it may be possible to fix the gauge and solve the linearized constraint equations in such a way that for the reduced linearized theory, the pullback of the symplectic current to a Cauchy surface Σ takes the form

$$\omega = \mathbf{W}_{\alpha\beta} \left(\psi_1^\alpha \frac{\partial \psi_2^\beta}{\partial t} - \psi_2^\alpha \frac{\partial \psi_1^\beta}{\partial t} \right)$$

where ψ^α denotes the dynamical variables for the reduced

linearized theory and $\mathbf{W}_{\alpha\beta}$ is constructed from the quantities appearing in the background solution. It follows that $\int_{\Sigma} \mathbf{W}_{\alpha\beta} \psi^{\alpha} \psi^{\beta}$ is conserved, and, if positive definite, yields an inner product \langle , \rangle . If h is the Hamiltonian for the reduced linearized theory, then

$$I = \frac{h(\psi, \psi)}{\langle \psi, \psi \rangle}$$

provides a variational principle, from which stability can be readily determined.